

Empirical Bayes

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Introduction

- ▶ Researchers increasingly have access to detailed, large data with unit identifiers
- ▶ The units (e.g., physicians, hospitals) may matter for outcomes of interest
- ▶ Developments in computing power allow analysis accounting for units
- ▶ A recent body of work on empirical Bayes (EB) methods provides tools for analyzing *unit-specific parameters* when *observations per unit are finite*

Note: this cyberseminar borrows heavily from Gu (2022) and Walters (2022)

Poll

How familiar are you with empirical Bayes methods?

1. I have used empirical Bayes methods in my work
2. I have some understanding of empirical Bayes methods but have not used them in my work
3. I have only heard of the term empirical Bayes
4. I have not heard of the term empirical Bayes

Outline

Basic Setup

Theory and Philosophy

Practice

Extensions

Connections

VA Applications

Basic Setup

- ▶ Patients i , assigned to one of J physicians
 - ▶ Assignment function $j(i)$; $N_j = \sum_i \mathbf{1}(j(i) = j)$ is count of patients assigned to j
- ▶ $Y_i(j)$ is the outcome (e.g., spending) for patient i when assigned to physician $j \in \{1, \dots, J\}$
- ▶ Simple additive model of potential outcomes:

$$Y_i(j) = \beta_j + \varepsilon_i$$

- ▶ β_j is the **value-added** of physician j
- ▶ $\beta_j - \beta_{j'}$ represents a treatment effect of being assigned to physician j instead of j'
- ▶ ε_i represents other patient characteristics. Normalize $E[\varepsilon_i] = 0$.

Object of Interest

- ▶ The object of interest in this model is a *unit-specific parameter* β_j or the set $\{\beta_j\}_{j \in \{1, \dots, J\}}$

- ▶ Contrast this with models for other empirical questions, e.g.,

$$Y_i = \beta D_i + \alpha_{j(i)} + \varepsilon_i$$

- ▶ Object of interest may be the effect β of a treatment D_i
 - ▶ α_j would be a nuisance parameter
- ▶ When interested in $\{\beta_j\}_{j \in \{1, \dots, J\}}$, important to ask how large is J and how many observations for each j
 - ▶ Fundamental issue in empirical Bayes: finite sample of observations for each j

Relevant Research and Policy Questions

- ▶ Questions
 - ▶ What is the value-added for a particular physician, e.g., β_1 ?
 - ▶ What does the distribution of $\{\beta_j\}_{j \in \{1, \dots, J\}}$ look like? Are there outliers?
 - ▶ Which physicians can we classify as being high performers, e.g., the top 10%?
- ▶ With infinite observations for each physician, these questions would be trivial
 - ▶ In practice, we have finite observations, sometimes very few, for each physician
 - ▶ Empirical Bayes methods can provide tools to answering these questions

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Value-Added Model Regression

- ▶ Recall the value-added model:

$$Y_i(j) = \beta_j + \varepsilon_i$$

- ▶ Assume that patients are randomly assigned to physicians
- ▶ Then can estimate value-added in an OLS regression:

$$Y_i = \beta_{j(i)} + \varepsilon_i$$

- ▶ By random assignment, $\varepsilon_i \perp\!\!\!\perp \beta_{j(i)}$ (can relax this with more complicated causal models)

Fixed Effects and Random Effects

- ▶ Two statistical assumptions about β_1, \dots, β_J :
 - ▶ Fixed effects: β_1, \dots, β_J are treated as unknown parameters
 - ▶ Random effects: β_1, \dots, β_J are treated as random variables with distribution G (i.e., $\beta_j \sim_{\text{i.i.d.}} G$)
- ▶ Two corresponding estimators:

- ▶ Fixed effect estimator:

$$\hat{\beta}_j^{FE}(\mathbf{Y}) = \frac{1}{N_j} \sum_i \mathbf{1}(j(i) = j) Y_i$$

Uses only data corresponding to $j(i) = j$.

- ▶ Empirical Bayes estimator with linear shrinkage (assume $E[\beta_j] = 0$):

$$\hat{\beta}_j^{EB}(\mathbf{Y}) = \lambda(\mathbf{Y}) \hat{\beta}_j^{FE}(\mathbf{Y})$$

$\lambda(\mathbf{Y})$ uses all data.

Objective of Effect Estimation

- ▶ If we are only interested in one parameter (e.g., β_1), then we may have a loss function as

$$L(\beta_1, \hat{\beta}_1(\mathbf{Y})) = (\beta_1 - \hat{\beta}_1(\mathbf{Y}))^2$$

I.e., our objective is to minimize the expected difference between β_1 and $\hat{\beta}_1$. In this case, $\hat{\beta}_1^* = \hat{\beta}_1^{FE}(\mathbf{Y})$, as $E[\hat{\beta}_1^{FE}(\mathbf{Y})] = \beta_1$.

- ▶ If we are interested in multiple parameters (e.g., β_1, \dots, β_J), then we may have a loss function as

$$\frac{1}{J} \sum_{j=1}^J L(\beta_j, \hat{\beta}_j(\mathbf{Y}))$$

The expectation of this is known as **compound risk**, and minimizing it is a **compound decision problem**

- ▶ Note: both of these are frequentist objectives

Theory

- ▶ Linear shrinkage estimator $\hat{\beta}_j^{EB}(\mathbf{Y}) = \lambda(\mathbf{Y}) \hat{\beta}_j^{FE}(\mathbf{Y})$ (under $E[\beta_j] = 0$, can be relaxed) produces lower compound risk than the fixed-effect estimator for any $J \geq 3$ (James and Stein 1961)
- ▶ Shrinkage estimator is biased for any individual β_j (i.e., $E[\hat{\beta}_j^{EB}(\mathbf{Y})] \neq \beta_j$) in return for better average performance over $j \in \{1, \dots, J\}$.
- ▶ Therefore, use empirical Bayes shrinkage when interested in performance of estimator over many units
- ▶ Empirical Bayes estimator uses all data:
 - ▶ “Borrowing strength from the ensemble” (Efron and Morris 1973; Morris 1983)
 - ▶ “Learning from the experience of others” (Efron 2012)

Philosophy of Random Effects

- ▶ Recall random effects definition: random variables with distribution G
- ▶ How do we think about the distribution G ?
- ▶ Literal view: observed units are random draws from a larger population of units; may be unsatisfying depending on the context (e.g., units are VA hospitals)

Philosophy of Random Effects

- ▶ Pragmatic view: even with a fixed number of units (e.g., VA hospitals), empirical Bayes allows provides useful insights
 - ▶ $\{\beta_j\}_{j=1}^J$ imply a (discrete) distribution G even with a fixed set of j ; continuous modeling of G can be viewed as a useful approximation
 - ▶ What is the best set of predictions of $\{\beta_j\}_{j=1}^J$ given the data? Other important policy-relevant questions can be illuminated by G
 - ▶ Distinction between random effects vs. fixed effects here is not about correlation with covariates but about focus on $\{\beta_j\}_{j=1}^J$

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Implementing Empirical Bayes

- ▶ Shrinkage depends on the distribution G , which is unknown
- ▶ Empirical Bayes involves plugging in estimates of G from the data \mathbf{Y} (recall the simple linear shrinkage $\lambda(\mathbf{Y})$)
- ▶ Parametric and non-parametric methods for approximating G

Parametric Normal-Normal Model

- ▶ Consider set of estimates of $\{\beta_j\}_{j=1}^J$ and corresponding standard errors: $\left\{ \left(\hat{\beta}_j, \mathbf{s}_j \right) \right\}_{j=1}^J$

- ▶ Assume normal-normal **hierarchical model**:

$$\beta_j \sim N(\mu, \sigma^2)$$

$$\hat{\beta}_j \mid \beta_j, \mathbf{s}_j^2 \sim N(\beta_j, \mathbf{s}_j^2)$$

- ▶ $G = N(\mu, \sigma^2)$ is a **mixing distribution**; $\hat{\beta}_j \mid \mathbf{s}_j \sim F_j = N(\mu, \sigma^2 + \mathbf{s}_j^2)$ (F_j is a **mixture distribution**)

- ▶ **Deconvolution**: estimating G from $\left\{ \left(\hat{\beta}_j, \mathbf{s}_j \right) \right\}_{j=1}^J$

- ▶ In parametric normal-normal model, this reduces to estimating **hyperparameters** μ and σ^2

Estimating Normal Hyperparameters

- ▶ Common approach:

$$\hat{\mu} = \frac{1}{J} \sum_{j=1}^J \hat{\beta}_j$$

$$\hat{\sigma}^2 = \frac{1}{J} \sum_{j=1}^J \left[(\hat{\beta}_j - \hat{\mu})^2 - \mathbf{s}_j^2 \right]$$

- ▶ Subtract out \mathbf{s}_j^2 to account for sampling error in $\hat{\beta}_j$ relative to β_j

Shrinkage and Posterior Means

- ▶ Posterior mean of β_j , given known hyperparameters and $(\hat{\beta}_j, \mathbf{s}_j)$:

$$\beta_j^* = E[\beta_j | \hat{\beta}_j, \mathbf{s}_j] = \left(\frac{\sigma^2}{\sigma^2 + \mathbf{s}_j^2} \right) \hat{\beta}_j + \left(\frac{\mathbf{s}_j^2}{\sigma^2 + \mathbf{s}_j^2} \right) \mu$$

- ▶ Shrinkage factor $\lambda = \frac{\sigma^2}{\sigma^2 + \mathbf{s}_j} \in [0, 1]$ reflects signal-to-noise ratio
- ▶ Linear regression interpretation: λ is coefficient in linear regression of β_j on $\hat{\beta}_j \Rightarrow$ in class of linear functions, β_j^* minimizes MSE for even non-normal G
- ▶ Empirical Bayes posterior mean plugs in estimated hyperparameters $(\hat{\mu}, \hat{\sigma}^2)$:

$$\hat{\beta}_j^* = \left(\frac{\hat{\sigma}^2}{\hat{\sigma}^2 + \mathbf{s}_j} \right) \hat{\beta}_j + \left(\frac{\mathbf{s}_j^2}{\hat{\sigma}^2 + \mathbf{s}_j} \right) \mu$$

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Incorporating Unit Covariates

- ▶ May observe different groups of units (e.g., nurse practitioners and physicians) or characteristics of units (e.g., provider gender, age); can use these for shrinkage
 - ▶ Akin to asking *which other units* should we learn from (c.f., Efron 2012)

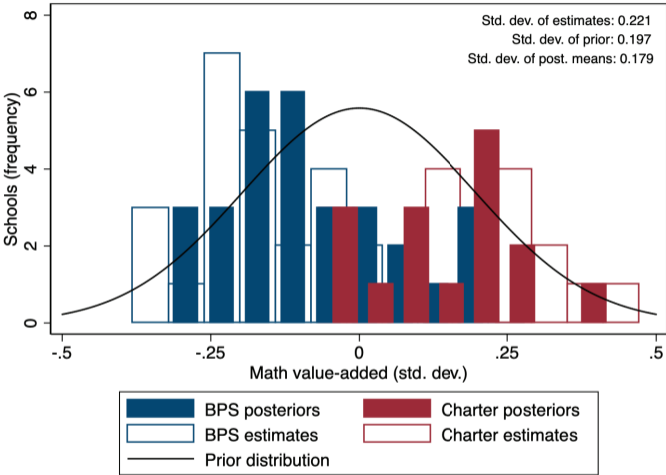
- ▶ Can model G with mean (and variance) accounting for covariates \mathbf{X}_j :

$$\beta_j | \mathbf{X}_j \sim N(\mathbf{X}_j' \gamma, \sigma_r^2)$$
$$\hat{\beta}_j | \beta_j, \mathbf{s}_j \sim N(\hat{\beta}_j, \mathbf{s}_j^2)$$

- ▶ Estimate γ from regressing $\hat{\beta}_j$ on \mathbf{X}_j ; deconvolve residuals $\hat{r}_j = \hat{\beta}_j - \mathbf{X}_j' \gamma$ (with knowledge of \mathbf{s}_j) to estimate σ_r^2 . For groups (e.g., nurse practitioners and physicians), could model group-specific $\sigma_{r(j)}^2$.
- ▶ Empirical Bayes posterior mean:

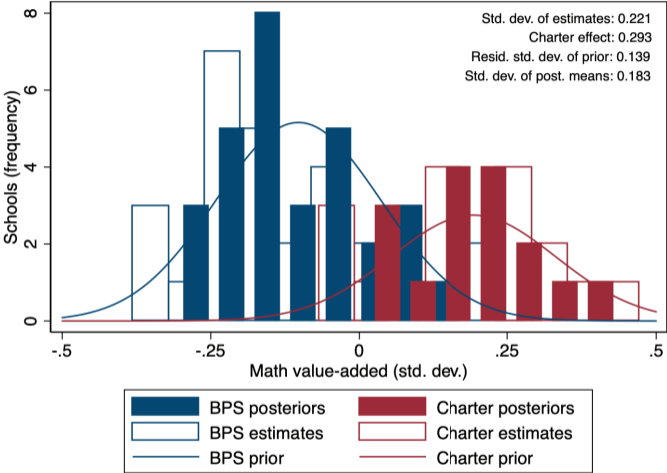
$$\hat{\beta}_j^* = \left(\frac{\hat{\sigma}_r^2}{\hat{\sigma}_r^2 + \mathbf{s}_j} \right) \hat{\beta}_j + \left(\frac{\mathbf{s}_j^2}{\hat{\sigma}_r^2 + \mathbf{s}_j} \right) \mathbf{X}_j' \hat{\gamma}$$

School Value-Added (Angrist et al. 2017)



Source: Walters (2022)

School Value-Added (Angrist et al. 2017)



Source: Walters (2022)

EB for Bias Correction

- ▶ Can use EB framework to improve predictions of parameters when we have multiple estimates, some possibly biased (Angrist et al. 2017)

- ▶ Suppose we have a precise but biased OLS estimate for β_j , with bias b_j :

$$\hat{\beta}_j^{OLS} \mid \beta_j, b_j, s_{j,OLS}^2 \sim N(\beta_j + b_j, s_{j,OLS}^2)$$

- ▶ Suppose we also have a noisy but (asymptotically) unbiased IV estimate:

$$\hat{\beta}_j^{IV} \mid \beta_j, s_{j,IV}^2 \sim N(\beta_j, s_{j,IV}^2)$$

- ▶ Suppose Hausman test rejects equality of $\hat{\beta}_j^{OLS}$ and $\hat{\beta}_j^{IV}$. Should we throw away $\hat{\beta}_j^{OLS}$?

EB for Bias Correction

$$\begin{aligned}\hat{\beta}_j^{OLS} \mid \beta_j, \mathbf{b}_j, \mathbf{s}_{j,OLS}^2 &\sim \mathbf{N}(\beta_j + \mathbf{b}_j, \mathbf{s}_{j,OLS}^2) \\ \hat{\beta}_j^{IV} \mid \beta_j, \mathbf{s}_{j,IV}^2 &\sim \mathbf{N}(\beta_j, \mathbf{s}_{j,IV}^2) \\ \beta_j &\sim \mathbf{N}(\mu, \sigma^2)\end{aligned}$$

► Use $\left\{ \left(\hat{\beta}_j^{OLS}, \hat{\beta}_j^{IV}, \mathbf{s}_{j,OLS}^2, \mathbf{s}_{j,IV}^2 \right) \right\}$ to estimate $G(\beta, \mathbf{b})$

► MSE-minimizing posterior $\hat{\beta}_j^* = E_{\hat{G}(\beta, \mathbf{b})} \left[\beta_j \mid \hat{\beta}_j^{OLS}, \hat{\beta}_j^{IV} \right]$

$$\hat{\beta}_j^* = \hat{\lambda}_{IV} \hat{\beta}_{j,IV} + \hat{\lambda}_{OLS} \left(\hat{\beta}_{j,OLS} - \hat{E}[\mathbf{b}_j] \right) + \left(1 - \hat{\lambda}_{IV} - \hat{\lambda}_{OLS} \right) \hat{\mu}$$

► Performs better than EB using only unbiased estimates, or $\hat{\beta}_{j,IV}^* = E_{\hat{G}(\beta)} \left[\beta_j \mid \hat{\beta}_j^{IV} \right]$

Normal Transformations

- ▶ Efron and Morris (1975): predict hits H_j out of N_j bats of baseball players for the remainder of the season

$$H_j \sim \text{Binom}(N_j, p_j)$$

- ▶ Transform H_j to an approximately normal distribution:

$$\tilde{H}_j = \sqrt{N_j} \arcsin(2H_j/N_j - 1) \approx N(\beta_j, 1),$$

$$\beta_j = \sqrt{N_j} \arcsin(2p_j - 1)$$

- ▶ Use realized $\hat{p}_j = H_j/N_j$ to calculate $\hat{\beta}_j$. $\beta_j \sim G = N(\mu, \sigma^2)$. Deconvolve to find G .
- ▶ EB prediction p_j^* (\mathbf{H}, \mathbf{N}) performs much better than using \hat{p}_j alone to predict H_j

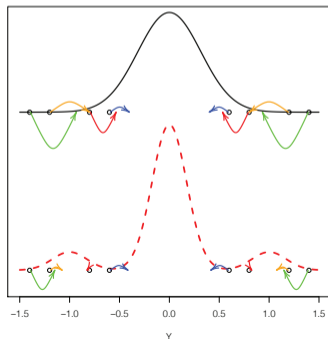
Non-Parametric G

- ▶ Recent advances estimate more flexible non-parametric G

$$(\beta_j, \mathbf{s}_j^2) \sim G$$

$$\hat{\beta}_j \mid \beta_j, \mathbf{s}_j^2 \sim N(\beta_j, \mathbf{s}_j^2)$$

- ▶ Simulated example: mixture of three normal distributions (Gu 2022)

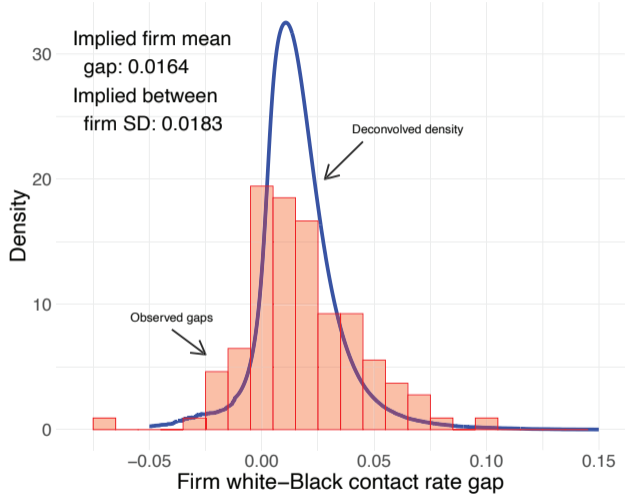


Non-Parametric G Techniques

$$z_j = \beta_j / s_j \sim G$$
$$\hat{\beta}_j \mid \beta_j, s_j^2 \sim N(\beta_j, s_j^2)$$

- ▶ Efron (2016): approximate G with flexible splines
 - ▶ Implement with `deconvolveR` R package (Narashimhan and Efron 2020)
- ▶ Non-parametric maximum likelihood estimator (NPMLE) (Robbins 1950): approximate G as discrete distribution with at most K mass points
 - ▶ Implement with `REBayes` R package (Koenker and Gu 2017)

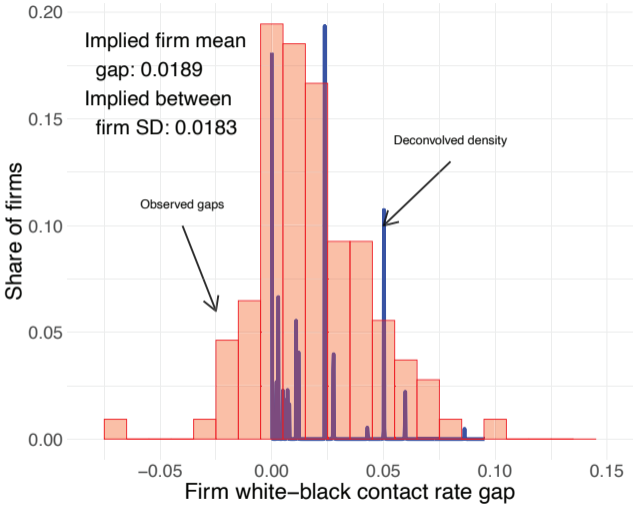
Non-Parametric G Illustration: Efron (2016)



Source: Kline et al. (2022)

Non-Parametric G Illustration: NPMLE

a) Race



Source: Kline et al. (2022)

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Machine Learning

- ▶ EB methods are closely related to **machine learning** (ML) with **regularized regressions**
 - ▶ Both have many (J) parameters; goal of both to improve predictions with finite observations per J
- ▶ Consider normal-normal model with J physicians and N patients per physician:

$$\begin{aligned} Y_i &= \beta_{j(i)} + \varepsilon_i \\ \varepsilon_i &\sim \mathcal{N}(0, \sigma_\varepsilon^2) \\ \beta_j &\sim \mathcal{N}(0, \sigma_\beta^2) \end{aligned}$$

- ▶ Recall unbiased fixed effect estimator: $\hat{\beta}_j^{FE} = \frac{1}{N} \sum_i \mathbf{1}(j(i) = j) Y_i$; using it is akin to **overfitting**, a problem ML seeks to solve
- ▶ EB posterior distribution for β_j is normal \Rightarrow posterior mean β_j^* = posterior mode, also known as **maximum a posteriori** (MAP)

Machine Learning

- ▶ Plugging in normal densities for ε_{ij} and β_j (i.e., G), we can solve for the MAP $(\beta_1^*, \dots, \beta_J^*)$:

$$\begin{aligned}(\beta_1^*, \dots, \beta_J^*) &= \arg \min_{(\beta_1, \dots, \beta_J)} \sum_{j=1}^J \sum_{i=1}^N \mathbf{1}(j(i) = j) (Y_i - \beta_j)^2 + \frac{\sigma_\varepsilon^2}{\sigma_\beta^2} \sum_{j=1}^J \beta_j^2 \\ &= \arg \min_{(\beta_1, \dots, \beta_J)} \sum_{j=1}^J \sum_{i=1}^N \mathbf{1}(j(i) = j) (Y_i - \beta_j)^2 + \lambda p(\beta_1, \dots, \beta_J)\end{aligned}$$

This is the solution to a regularized regression, with penalty $p(\cdot)$ and tuning parameter $\lambda = \sigma_\varepsilon^2 / \sigma_\beta^2$

- ▶ The particular regularized regression is known as **ridge regression**
- ▶ In spirit of EB, data are used to choose λ

Machine Learning

- ▶ Thus, ML regularization often has EB interpretation
 - ▶ Ridge regression estimates (L2 penalization): posterior means/modes from a model with normal priors
 - ▶ LASSO regression estimates (L1 penalization): posterior modes from double exponential (Laplace) priors
- ▶ May be useful to think about implicit EB prior distribution of parameters (i.e., G)
 - ▶ Some ML approaches will perform better under certain implicit parameter prior distributions (Abadie and Kasy 2019)

Multiple Hypothesis Testing

- ▶ With \hat{G} and $(\hat{\beta}_j, s_j^2)$, can use EB to make relevant policy assessments that are compound decision problems, e.g.,
 - ▶ Which doctors are in the top quintile of performance ($\beta_j > G^{-1}(0.8)$)?
 - ▶ Which VA hospitals are discriminating against Black patients ($\beta_j > 0$)?
- ▶ Such problems are “large-scale inference” problems, closely related to multiple-testing problems (Efron 2012)

Multiple Hypothesis Testing

- ▶ Example: Kline et al. (2022) interested in classifying firms as discriminating against Black applicants (see also Gu and Koenker (2022))
 - ▶ Send random applications with Black-sounding vs. white-sounding names to J firms
 - ▶ Estimate $\left\{ \left(\hat{\beta}_j, s_j^2 \right) \right\}_{j=1}^J$ for J firms
 - ▶ Can perform one-tailed t -test: $\beta_j = 0$ vs. $\beta_j > 0$. Implies test statistic $z_f = \hat{\beta}_j / s_j$ and p -value $p_j = 1 - \Phi(z_j)$.
- ▶ Decision rule: classify firm as discriminatory if $p_j \leq \bar{p}$
 - ▶ How many mistakes do we expect to make (i.e., **false discovery rate** or FDR) for a given \bar{p} ? What should we pick for \bar{p} ?

Multiple Hypothesis Testing

- ▶ From definition of p -value, $\bar{p} = \Pr(p_j \leq \bar{p} | \beta_j = 0)$; interested in $FDR = \Pr(\beta_j = 0 | p_j \leq \bar{p})$

- ▶ By Bayes rule,

$$\begin{aligned} FDR(\bar{p}) &= \Pr(\beta_j = 0 | p_j \leq \bar{p}) \\ &= \frac{\Pr(p_j \leq \bar{p} | \beta_j = 0) \Pr(\beta_j = 0)}{\Pr(p_j \leq \bar{p})} \\ &= \frac{\bar{p} \Pr(\beta_j = 0)}{\Pr(p_j \leq \bar{p})} \end{aligned}$$

- ▶ $\Pr(p_j \geq \bar{p})$ is a function of the data; $\Pr(\beta_j = 0)$ depends on G
- ▶ Set $FDR(\bar{p})$ based on cost of type I (false positives) vs. type II errors (false negatives)

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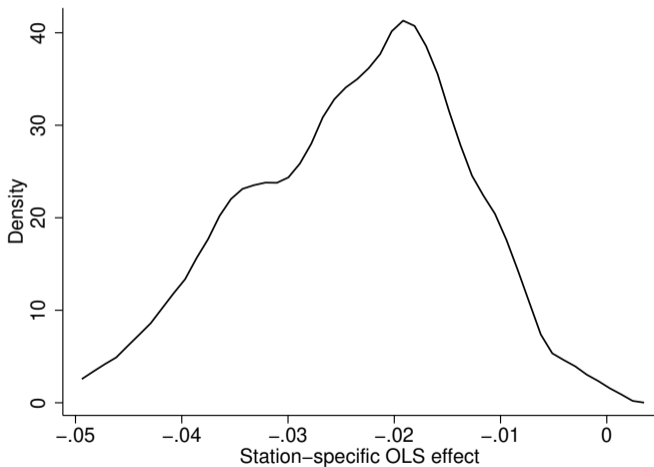
VA Applications

VA vs. Non-VA Care

- ▶ Chan et al. (2022): quasi-experimental assignment of ambulances to dually eligible veterans above age 65
 - ▶ Veterans may receive care at VA or non-VA emergency departments (EDs)
 - ▶ IV approach: ambulances have different propensities to transport veterans to the VA
 - ▶ Condition on zip code: each location is part of a different quasi-experiment (each with its own VA and non-VA hospitals of interest)
- ▶ Main finding: VA hospitals reduce mortality by 45% in IV design; robust 21% reduction in mortality by OLS
- ▶ How might this result vary across VA stations?

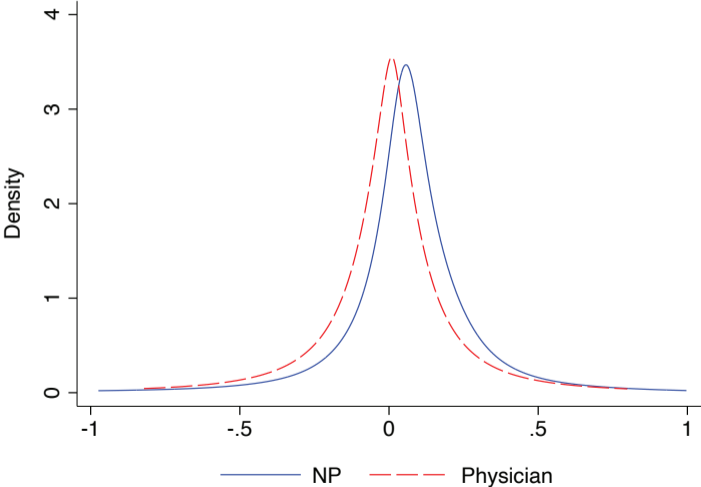
VA vs. Non-VA Care

Station-specific VA mortality effect (OLS design): all stations reduce mortality



NP vs. Physician ED Productivity

Deconvolved distributions of productivity: 38% overlap in productivity



Conclusion

- ▶ Empirical Bayes methods provide tools to jointly assess effects across important units of interests (e.g., physicians, hospitals)
- ▶ The increasing granularity of data (including at the VA), combined with computational tools, has led to a rise in recent methods and applications
- ▶ Compound decision problems and large-scale inference made possible by these methods are extremely policy-relevant

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